

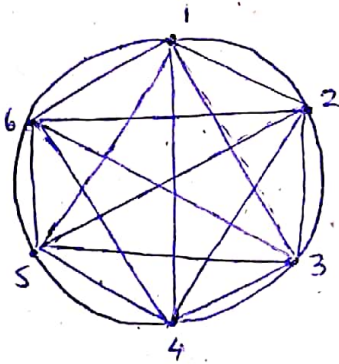
(P3) Figure shows a mechanism. Various dimensions are :  $O_1O_2 = 150 \text{ mm}$ ,  $O_1Q = 85 \text{ mm}$ ,  $O_2P = 75 \text{ mm}$ ,  $PR = 405 \text{ mm}$ .

Using instantaneous centre of rotation method, find the velocity of the slider R at the crank position shown in the figure, if the crank is rotating at 175 rpm in the anticlockwise direction. Find the angular velocity of link PR at the same instant. (Safari 16)(Q 2b) (10)

Solution : Since there are 6 links in this mechanism,  

$$N = \frac{n(n-1)}{2} = \frac{6(5)}{2} = 15$$

Hence, there are 15 Instantaneous centres in this mechanism.



$I_{12}, I_{23}, I_{34}, I_{45}, I_{56}, I_{16}$  are easily located.

links →	1	2	3	4	5	6
I.C.	√12	√23	√34	√45	√56	
	√13	√24	√35	√46		
	√14	√25	√36			
	√15	√26				
	√16					

To locate  $I_{15}$  - Draw dotted line 15.  $I_{15}$  will lie on the intersection of lines passing through  $I_{16}, I_{56}$  and  $I_{14}, I_{45}$ . Thus,  $I_{15}$  can be located. Make the line 15 dark.

In a similar way, locate the other instantaneous centres of rotation.

1) To find velocity of slider  $R$  (link 6) The angular velocity of crank  $O_1Q$  (link 2) is known. Hence consider the I centre

$I_{26}$ .

Consider  $I_{26}$  to be on link 2 and assume that link 2 is rotating about  $I_{12}$ .

$$\therefore V_{I_{26}} = \{l(I_{12} I_{26})\} \cdot \omega_2$$

$$\therefore V_{I_{26}} = (0.04) \left( \frac{2\pi(175)}{60} \right)$$

$$\therefore \underline{V_{I_{26}} = 0.257 \text{ m/s}}$$

Now consider link 6 to be a disc containing  $I_{26}$  and rotating about  $I_{16}$ . (\*)

Since  $I_{16}$  is at  $\infty$ ,  $l(I_{26} I_{16}) = l(R I_{16})$

Hence since point  $R$  and  $I_{26}$  are on the same link, they will have the same velocity due to their equal distance from  $I_{16}$ .

$$\therefore \underline{V_R = V_{I_{26}} = 0.257 \text{ m/s}}$$

2) To find  $\omega_5$  :

$$\frac{\omega_5}{\omega_2} = \frac{l(I_{25} I_{12})}{l(I_{25} I_{15})}$$

$$\therefore \omega_5 = \frac{2\pi(175)}{60} \cdot \frac{(12)}{(644)}$$

$$\therefore \underline{\omega_5 = 0.34 \text{ rad/s}} \rightarrow$$

(The direction is same as that of  $\omega_2$ , because  $I_{12}$  and  $I_{15}$  lie on the same side of  $I_{25}$ ).

\* All points on a sliding link have the same velocity. Hence if  $I_{26}$  is considered to be on link 6, velocity of link 6 will be equal to velocity of  $I_{26}$ .  $\therefore \underline{V_R = V_{I_{26}} = 0.257 \text{ m/s}}$



P4) In the mechanism shown in the figure, O and Q are fixed centres. If the crank OC rotates at a uniform speed of 120 rpm in clockwise direction, find the angular velocity of links CP, PA and AQ and linear velocity of slider P by instantaneous centre method. Assume following data:

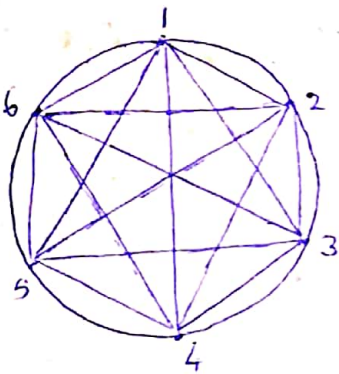
- OC = 125 mm
- CP = 500 mm
- AQ = 250 mm
- AP = 125 mm

36 marks  
May 99  
(1997)

(Nov. 93) (Q1) (16)

Solution: Locate all the I centres first.

$$N = \frac{n(n-1)}{2} = \frac{6(5)}{2} = 15$$



Links →	1	2	3	4	5	6
	12	23	34	45	56	
	13	24	35	46		
	14	25	36			
	15	26				
	16					

Thus, all the I centres can be located.

$\omega_2$  is known. We have to find  $\omega_3$ ,  $\omega_5$ , and  $\omega_6$ .

$$1) \frac{\omega_3}{\omega_2} = \frac{l(I_{23} I_{12})}{l(I_{23} I_{13})} = \frac{0.125}{0.695}$$

$$\therefore \omega_3 = \frac{0.125}{0.695} \left( \frac{2\pi(120)}{60} \right)$$

$$\therefore \omega_3 = 2.26 \text{ rad/s } \curvearrowright$$

( $I_{12}$  and  $I_{13}$  lie on opposite sides of  $I_{23}$ ).

$$2) \frac{\omega_5}{\omega_2} = \frac{l(I_{25} I_{12})}{l(I_{25} I_{15})} = \frac{0.918}{1.525}$$

$$\therefore \omega_5 = \frac{0.918 \cdot 2\pi(120)}{1.525 \cdot 60} = 7.57 \text{ rad/s } \curvearrowright$$

( $I_{12}$  and  $I_{15}$  lie on the same side of  $I_{25}$ ).

$$3) \frac{\omega_6}{\omega_2} = \frac{\lambda(I_{26} \cdot I_{12})}{\lambda(I_{26} \cdot I_{16})} = \frac{0.110}{0.230}$$

$$\therefore \omega_6 = \frac{0.110}{0.230} \times \frac{2\pi(120)}{60}$$

$$\therefore \omega_6 = \underline{6.01 \text{ rad/s}} \curvearrowright$$

4) To find linear velocity of slider P is that of link 4, when angular velocity of link 2 is known. Consider their common instant centre,  $I_{24}$ .

Consider link 2 to be a disc, containing  $I_{24}$  and rotating about  $I_{12}$ .

$$\therefore V_{I_{24}} = \lambda(I_{24} \cdot I_{12})(\omega_2)$$

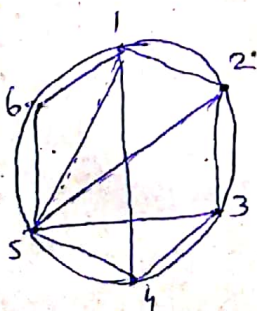
$$\therefore V_{I_{24}} = \frac{2\pi(120)}{60} \times \frac{0.110}{0.230}$$

$$\therefore V_{I_{24}} = \underline{1.38 \text{ m/s}}$$

Now consider link 4 to be a disc, containing  $I_{24}$  and rotating about  $I_{14}$ .  $I_{14}$  is at  $\infty$ , and hence  $\forall \lambda(I_{14} \cdot P) = \lambda(I_{14} \cdot I_{24})$ .

Hence, the velocity of the slider will be equal to that of  $I_{24}$ .

$$\therefore V_P = V_{I_{24}} = \underline{1.38 \text{ m/s}}$$



We can obtain  $V_p$  also by the following ways -

1) Point P lies on ~~link~~ link 3. Link 3 can be assumed to be  $\rho$  having a purely rotary motion about the frame link 1, about  $I_{13}$ .

$$\begin{aligned}\therefore V_p &= r(I_{13} \cdot P) \cdot (\omega_3) \\ &= (0.61)(2.26) \\ &= 1.38 \text{ m/s.}\end{aligned}$$

2) Point P also lies on link 5. Link 5 can be assumed to be having a purely rotary motion about the frame link 1, about  $I_{15}$ .

$$\begin{aligned}\therefore V_p &= r(I_{15} \cdot P) (\omega_5) \\ &= (0.18)(7.57) \\ &= 1.36 \text{ m/s.}\end{aligned}$$

3)  $V_p$  can be <sup>also</sup> obtained by knowing  $\omega_6$  (any link for that matter)

Consider  $I_{46}$  is common I center of link 4 & 6.

Consider  $I_{46}$  to be on link 6 and link 6 to be rotating about  $I_{16}$ .

$$\begin{aligned}\therefore V_{I_{46}} &= r(I_{46} - I_{16})(\omega_6) \\ &= (0.23)(6.01) \\ &= 1.38 \text{ m/s.}\end{aligned}$$

Now consider  $I_{46}$  to be on link 4, and link 4 to be rotating about  $I_{14}$ .

Since  $r(I_{46} - I_{14}) = r(I_{14} \cdot P)$ ,  
velocity of link 4 (i.e. point P) will be the same as that of  $I_{46}$ .

$$\therefore V_p = V_{I_{46}} = 1.38 \text{ m/s.}$$

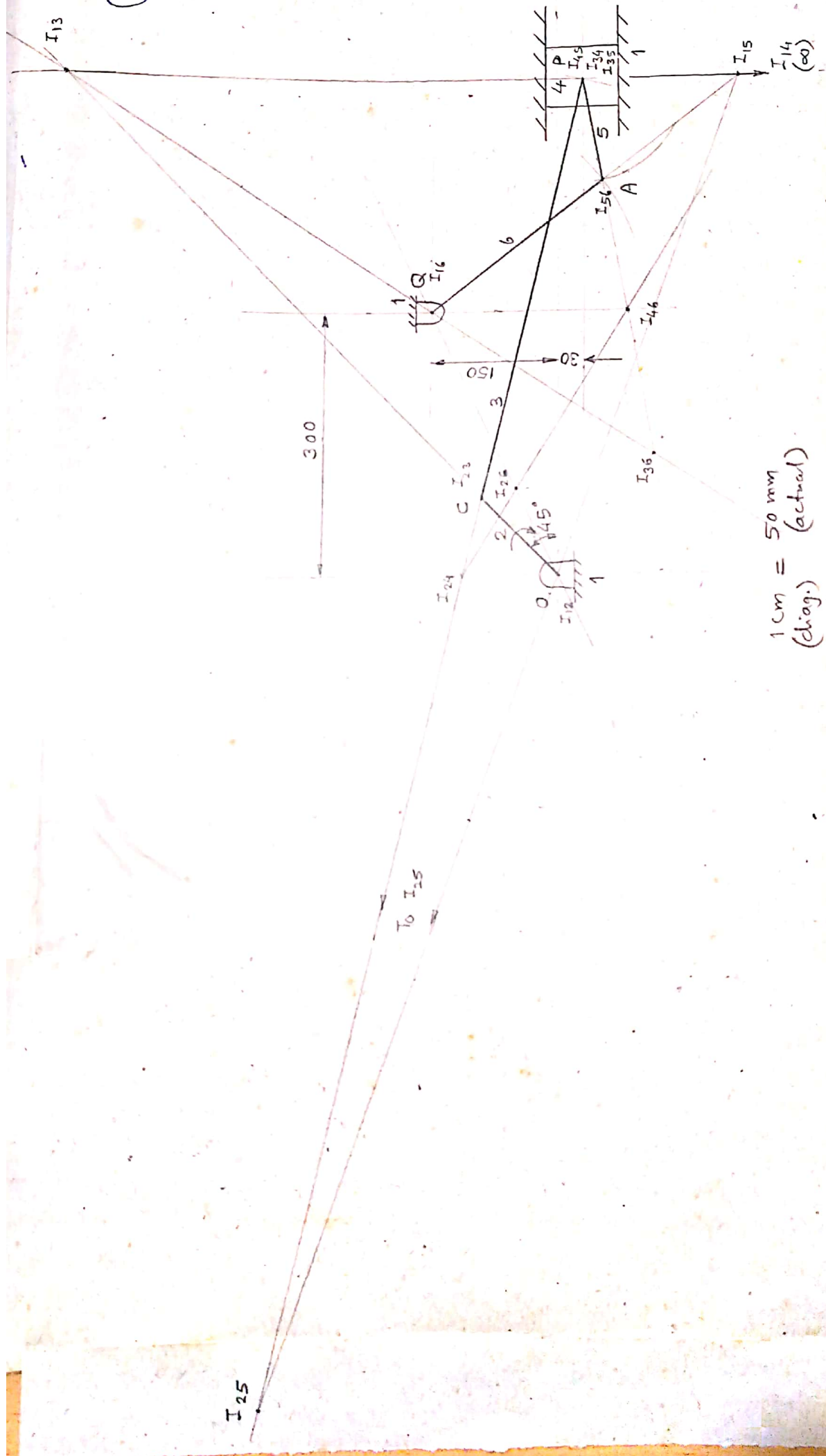
$$V_{I_{46}} = \omega_6 \times l(I_{46} - I_{16}) = 6.01 \times 0.23 = 1.38 \text{ m/s}$$

$$V_{I_{34}} = \omega_3 \times l(I_{34} - I_{13}) = \frac{2.26 \times 0.825}{2.26 \times 0.61} = 1.38 \text{ m/s}$$

$$V_{I_{45}} = \omega_5 \times l(I_{45} - I_{15}) = 7.57 \times 0.185 = 1.40 \text{ m/s}$$

$$V_{I_{24}} = \omega_2 \times l(I_{24} - I_{12}) = \frac{0.11}{12.57} \times 0.11 = 1.38 \text{ m/s}$$

P4



1 cm = 50 mm  
(diag.) 50 mm (actual)



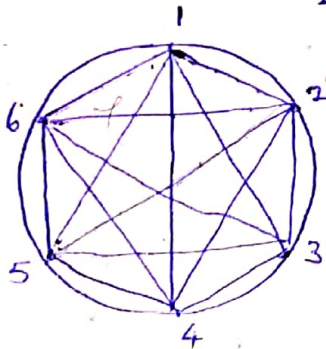
(P5) For the configuration showing in the figure, with the particulars given below, enumerate and locate all the I centers of velocity and hence find the velocity of slider D and the angular velocity of CD.

OA = 100 mm, OA = 200 mm, QC = 150 mm, CD = 500 mm,  $\omega_{OA}$  about O = 120 rpm  $\rightarrow$

(सिद्ध 72)(256)(10)

Solution

$$N = \frac{6(5)}{2} = 15$$



links	1	2	3	4	5	6
	12	23	34	45	56	
	13	24	35	46		
	14	25	36			
	15	26				
	16					

Thus, all the I centers can be located.

1) To find  $V_d$  - is to find velocity of slider 6.

$$V_d = V_6$$

$$\omega_{OA} = \frac{2\pi(120)}{60} = 12.57 \text{ rad/s} \rightarrow = \omega_2$$

Now, Consider  $I_{26}$ . Consider link 2 to be containing  $I_{26}$  and rotating about  $I_{12}$ .

$$\begin{aligned} \therefore V_{I_{26}} &= \lambda(I_{26} I_{12})(\omega_2) \\ &= 0.82 \text{ m/s.} \end{aligned}$$

Now consider link 6 to be containing  $I_{26}$  and rotating about  $I_{16}$ . Since  $I_{16}$  is at  $\infty$ ,

$$\lambda(I_{16} I_{26}) = \lambda(I_{16} - 6)$$

$\therefore$  Velocity of slider 6 will be the same as that of  $I_{26}$ .  $\therefore V_d = V_6 = 0.82 \text{ m/s.}$

2) To find angular velocity of link CD i.e. link 5.

$$\frac{\omega_5}{\omega_2} = \frac{I_{25} - I_{12}}{I_{25} - I_{15}}$$

$$\therefore \omega_5 = (12.57) \left( \frac{0.0875}{0.605} \right)$$

$$\therefore \omega_5 = 1.82 \text{ rad/s} \quad \curvearrowright$$

(Both  $I_{12}$  and  $I_{15}$  lie on the same side of  $I_{25}$ ).

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1 cm = 50 mm  
(diag.) (actual)

